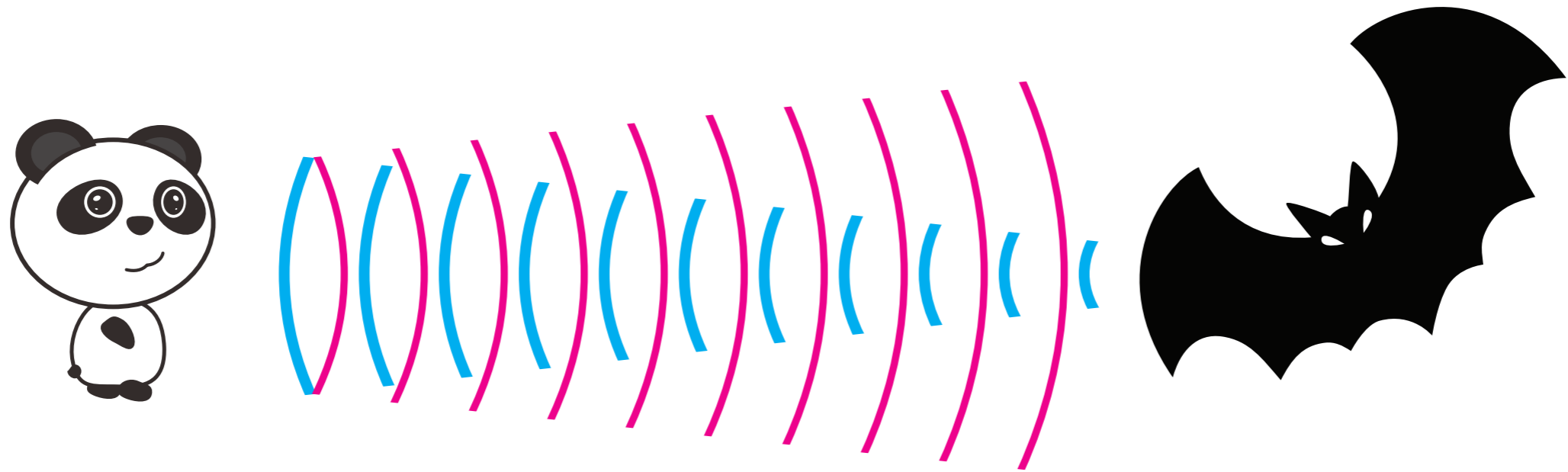


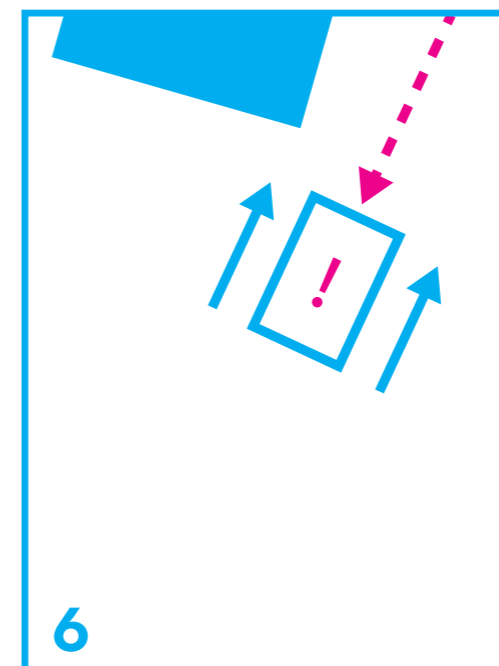
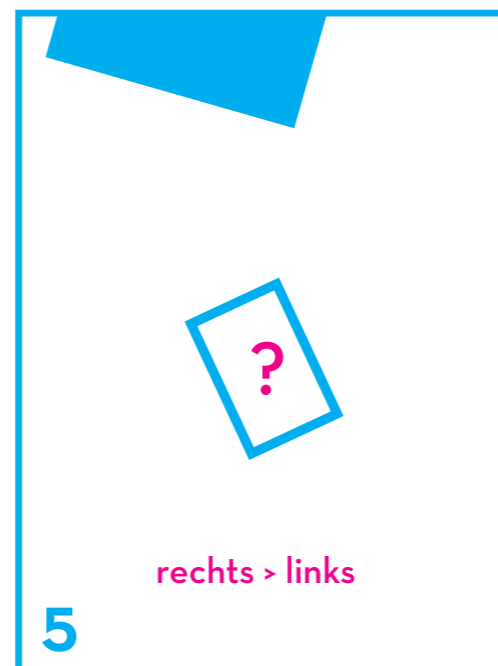
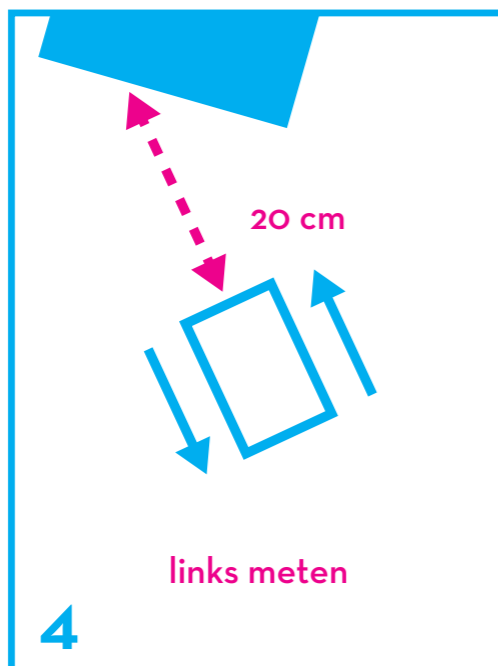
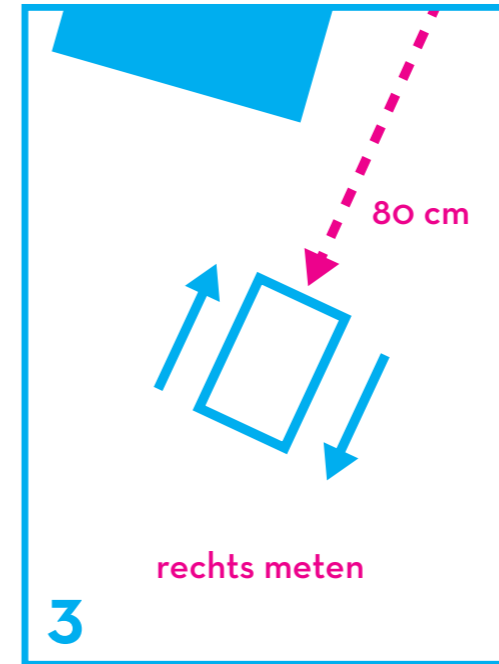
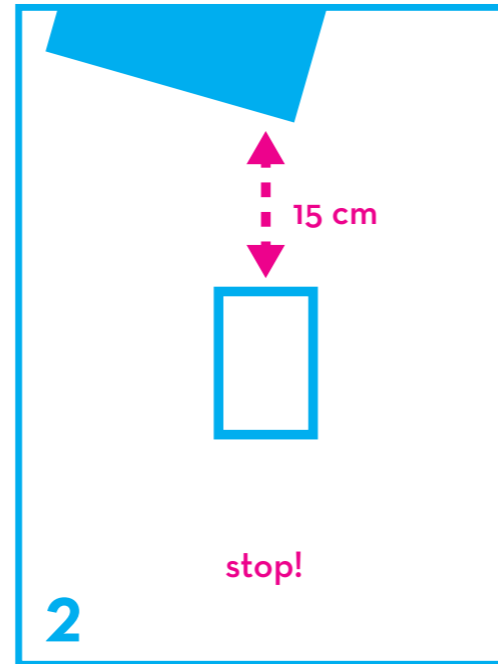
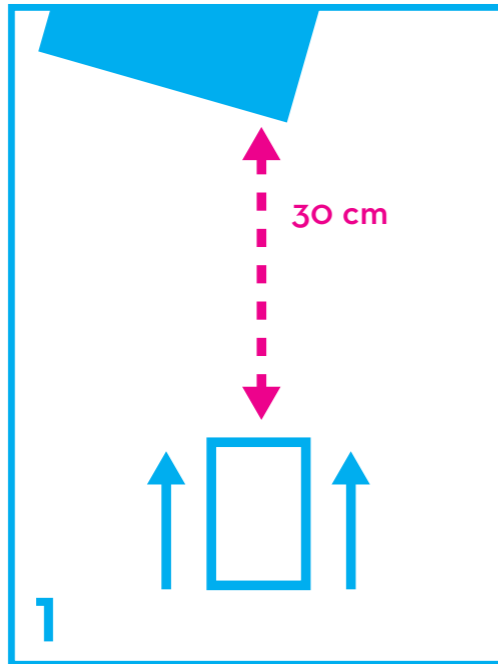


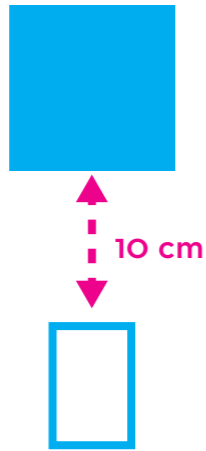
robot



geen robot

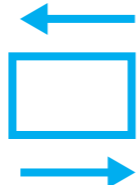






Als de robot rijdt en een obstakel meet binnen 10 cm, stop!

1




draai dan 90° naar links

2




rij klein stukje vooruit

3



draai dan 90° naar rechts

4



als de gemeten afstand kleiner dan 10cm is, ga dan terug naar stap B

5



Als de weg vrij is, rij vooruit

6